

Journal of Dynamic Systems, Measurement, and Control

Publication Title History

September, 2010 | Volume 132 | Issue 5

Email Alerts | RSS 
BASIC
VIEW | EXPANDED VIEW

Research Papers

Magnetically Suspended VSCMGs for Simultaneous Attitude Control and Power Transfer IPAC Service

Junyoung Park and Alan Palazzolo

J. Dyn. Sys., Meas., Control. 2010;132(5):051001-051001-15. doi:10.1115/1.4002105.

Output Saturation in Electric Motor Systems: Identification and Controller Design

Kyoungchul Kong, Helge C. Kniep and Masayoshi Tomizuka

J. Dyn. Sys., Meas., Control. 2010;132(5):051002-051002-8. doi:10.1115/1.4001792.

Dynamic Modelling and Control of Semifree-Piston Motion in a Rotary Diesel Generator Concept

J. F. Dunne

J. Dyn. Sys., Meas., Control. 2010;132(5):051003-051003-12. doi:10.1115/1.4001794.

Multibody Dynamic Model of Web Guiding System With Moving Web

Lei Yu, Zhihua Zhao and Gexue Ren

J. Dyn. Sys., Meas., Control. 2010;132(5):051004-051004-10. doi:10.1115/1.4001797.

Robust Fuzzy Tracking Control Design for a Class of Nonlinear Stochastic Markovian Jump Systems

Ran Huang, Yan Lin and Zhongwei Lin

J. Dyn. Sys., Meas., Control. 2010;132(5):051005-051005-9. doi:10.1115/1.4001850.

Dynamic Thermomechanical Modeling of a Wet Shape Memory Alloy Actuator

Joel D. Ertel and Stephen A. Mascaró

J. Dyn. Sys., Meas., Control. 2010;132(5):051006-051006-9. doi:10.1115/1.4002067.

New Stabilization Schemes for Linear Hybrid Systems With Time-Varying Delays

Magdi S. Mahmoud and Sami A. Elferik

J. Dyn. Sys., Meas., Control. 2010;132(5):051007-051007-11. doi:10.1115/1.4002102.

Robust Stochastic Design of Linear Controlled Systems for Performance Optimization

Alexandros A. Taflanidis, Jeffrey T. Scruggs and James L. Beck

J. Dyn. Sys., Meas., Control. 2010;132(5):051008-051008-15. doi:10.1115/1.4001849.

PCCI Control Authority of a Modern Diesel Engine Outfitted With Flexible Intake Valve Actuation

Anup M. Kulkarni, Karla C. Stricker, Angeline Blum and Gregory M. Shaver

J. Dyn. Sys., Meas., Control. 2010;132(5):051009-051009-15. doi:10.1115/1.4002106.

Polynomial Chaos Based Design of Robust Input Shapers

Tarunraj Singh, Puneet Singla and Umamaheswara Konda

J. Dyn. Sys., Meas., Control. 2010;132(5):051010-051010-13. doi:10.1115/1.4001793.

Robust Impedance Control of Manipulators Carrying a Heavy Payload

Farhad Aghili

J. Dyn. Sys., Meas., Control. 2010;132(5):051011-051011-8. doi:10.1115/1.4001898.

Technical Briefs

Parameter Uncertainty Modeling Using the Multidimensional Principal Curves

M. Sepasi, F. Sassani and R. Nagamune

J. Dyn. Sys., Meas., Control. 2010;132(5):054501-054501-7. doi:10.1115/1.4001791.

Combined Controller for Test System of High Capacity Hydraulic Pump

Wenjun Meng and Jeffrey C. Suhling

J. Dyn. Sys., Meas., Control. 2010;132(5):054502-054502-7. doi:10.1115/1.4001925.

Mechatronic Model and Experimental Validation of a Pneumatic Servo-Solenoid Valve

Massimo Sorli, Giorgio Figliolini and Andrea Almondo

J. Dyn. Sys., Meas., Control. 2010;132(5):054503-054503-10. doi:10.1115/1.4002065.

Delay Dependent Robust Stabilization for Systems With Uncertain Time Varying Delays

El Houssaine Tissir

J. Dyn. Sys., Meas., Control. 2010;132(5):054504-054504-7. doi:10.1115/1.4002066.

Quantitative Fault Tolerant Control Design for a Leaking Hydraulic Actuator

Mark Karpenko and Nariman Sepehri

J. Dyn. Sys., Meas., Control. 2010;132(5):054505-054505-7. doi:10.1115/1.4001707.
